Colimitation of decomposition by substrate and decomposers – a comparison of model formulations

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Abstract. Decomposition of soil organic matter (SOM) is limited by both the available substrate and the active decomposer community. The understanding of this colimitation strongly affects the understanding of feedbacks of soil carbon to global warming and its consequences. This study compares different formulations of soil organic matter (SOM) decomposition. We compiled formulations from literature into groups according to the representation of decomposer biomass on the SOM decomposition rate a) non-explicit (substrate only), b) linear, and c) non-linear. By varying the SOM decomposition equation in a basic simplified decomposition model, we analyzed the following questions. Is the priming effect represented? Under which conditions is SOM accumulation limited? And, how does steady state SOM stocks scale with amount of fresh organic matter (FOM) litter inputs? While formulations (a) did not represent the priming effect, with formulations (b) steady state SOM stocks were independent of amount of litter input. Further, with several formulations (c) there was an offset of SOM that was not decomposed when no fresh OM was supplied. The finding that a part of the SOM is not decomposed on exhaust of FOM supply supports the hypothesis of carbon stabilization in deep soil by the absence of energy-rich fresh organic matter. Different representations of colimitation of decomposition by substrate and decomposers in SOM decomposition models resulted in qualitatively different long-term behaviour. A collaborative effort by modellers and experimentalists is required to identify formulations that are more or less suitable to represent the most important drivers of long term carbon storage.

1 Introduction

Plant litter or fresh organic matter (FOM) that enters the soil is decomposed by decomposer communities. In this process a part of the FOM is transformed to soil organic matter (SOM) and most of the carbon is released as CO$_2$ to the atmosphere. The understanding of the colimitation of the decomposition of FOM and SOM by the available substrate and the decomposers strongly affects the understanding of feedbacks of soil carbon to global change (Fang et al., 2005) and hence the understanding and consequences of global change (Jones et al., 2005).

This article studies the long-term consequences of several modelling assumptions regarding the decomposition process. It answers the following question: What decomposition formulations have been applied in SOM decomposition models, what are their underlying assumptions, and how can they be classified? What are their long-term implication for soil carbon storage? This is approached first, by reviewing the assumptions of several formulations of decomposition and second, by comparing the steady states of a basic minimal model, in which the decomposition equation was modified.

The colimitation of decomposition is represented in various ways in models that describe decomposition at daily resolution at plot-scale (Sect. 3.1). However, the assumption of different decomposer communities that mutually independent decompose different kinds of substrates has led to a widely used representation of decomposition at decadal to millennial time scales that is focused on substrate only (Paustian et al., 1997).

The observation of the priming effect (e.g. Kuzyakov et al., 2000) challenges the assumption of independent decomposition. In the modelling context we define priming as the effect
that decomposition of one soil carbon pool is influenced by the dynamics of another soil carbon pool. Based on observations of priming Fontaine and Barot (2005) suggest a formulation of SOM decomposition that results in SOM accumulation that is only limited by nitrogen availability for the SOM decomposers. This implies a completely different long-term dynamics compared to most commonly used models, where the carbon pools at steady state are constant and depend linearly on the fresh organic matter input. This contradiction warrants a closer review of different representations of various used decomposition equations and their underlying assumptions.

There are several good reviews and comparisons of SOM decomposition models. Van Veen and Frissel (1981a) group models that particularly take account of the role of microorganisms in mineralization versus simplified models that are more generically applicable. Paustian (1994) contrast organism oriented versus process oriented models. McGill (1996) compares 10 process-based models against long term field data and propose a classification scheme. The scheme distinguishes amongst others for kinetic versus biochemical or functional litter and SOM compartmentalization, which relates to representation of decomposer biomass in the models. Molina and Smith (1998) give a good general introduction into the historical evolution and various concepts of SOM models. Smith et al. (1998) focus on the purpose of the various models and summarize the reviews of Paustian, McGill, and Molina and Smith. Paustian et al. (1997) compare short-term decomposition and equilibrium states of several conceptual model formulations and three full models. Chertov et al. (2007) compare three conceptually different models against data from incubation studies. There are also more current reviews emphasizing on soil models for cropping systems (Shibu et al., 2006; Manlay et al., 2007), the stabilization by microbial metabolites or dead microbial biomass. Both Six et al. (2004), and the general role of soils (Yadav and Malanson, 2007).

However, all the above reviews are difficult to interpret in respect to different representations of colimitation of decomposition by substrate and decomposers because they compare full soil carbon models that differ in many aspects. Hence, this study reviews modelling literature with the explicit focus on this colimitation. Further, it compares various formulations by substituting them into a common basic model and by calculating the models steady states as a representation of the essentials of long-term behaviour. The study shows that the long-term consequences of formulations of decomposition qualitatively differ by the representation of the active decomposer in the description of SOM decomposition.

2 Methods

In a first step we compiled formulations of SOM decomposition from literature and summarized their underlying assumptions. The original formulations were simplified in a way so that only the factors and terms relating to substrate and decomposer biomass were included. Other drivers such as temperature, moisture, soil texture or nutrient availability were assumed to be constant and lumped into constants.

We grouped the equations in three groups a) “non-explicit”, b) “linear”, and c) “nonlinear” according to the representation of decomposer biomass in the SOM decomposition equations. In most cases this corresponded to similar assumptions and consequences for long term carbon storage.

In a second step we compared long-term consequences of the formulations. Following the conclusion of Jans-Hammermeister and McGill (1997) we compared only one contrasting component of system models, in our case the decomposition equations. We accomplished this by setting up a simplified minimal model system (Sect. 2.1) and substituted different versions of decomposition equations into this common model. Next, we calculated carbon pool sizes and fluxes as a function of model parameters at system steady state. Steady state represented the essential characteristics of the long-term behaviour and long-term consequences of the formulation of SOM decomposition. The following questions were addressed.

- Is the priming effect simulated?
- Is the SOM accumulation limited, i.e. under which conditions does an steady state of SOM exist?
- How does the steady state of SOM scale with input of fresh organic material (FOM)?
- Is there a positive steady state of SOM for FOM assimilation approaching zero?

Steady states were calculated analytically by setting the derivative of the model equations to zero. At a few cases the function of the steady state was not defined at zero litter input, and we hence calculated the limit of the function for litter input approaching zero.

2.1 Model system

In order to compare the different decomposition formulations, we inserted them into the same minimal SOM decomposition model. A flowchart of the system is given in Fig. 1. The minimal system considered only one pool of SOM (S) of a single quality. The SOM was decomposed according to the equations \( d \), that we compared. During decomposition a part \( e \) of the decomposed SOM was assimilated by the active decomposers \( A \) and the other part was respired as growth respiration. The carbon in active decomposers was respired as maintenance respiration \( r \) or entered the SOM as a flux \( s \) of microbial metabolites or dead microbial biomass. Both fluxes were described by a first order kinetics. Pool sizes were expressed in weight per volume (kg/m\(^3\)) and the time was expressed in years. We assumed an additional source of carbon \( i_F \) that is available to the active SOM decomposers.
We were interested in the qualitative behaviour in steady state for a given input of FOM and given, i.e. constant, environmental conditions. Therefore, the minimal model abstracted from the effects of environmental conditions such as temperature, soil moisture or texture, on the various model parameters. Further the minimal model did not account for interactions with other elements such as nitrogen or phosphorus.

The system was described by the following equations.

\[
\frac{dA}{dt} = i_F + \epsilon dS - (s + r)A \\
\frac{dS}{dt} = sA - dS
\]

2.2 Artificial model calibration experiment

In order to demonstrate that incubation priming experiments can be useful to discriminate between different model formulations, we devised an artificial model calibration experiment. We prescribed an initial amount and isotopic composition of SOM (7.0 kg, \( R_{C14} = 1 \times 10^{-12} \)) and a pulse input of labelled FOM (0.1 kg, \( R_{C14} = 10 \times 10^{-12} \)). We used the model system (Eqs. 1–2) and decomposition formulation (10) to generate a timeseries of the amount of carbon in respired CO₂ and its isotopic composition. Next, we added normally distributed measurement errors to the timeseries (\( \epsilon = 40\% \) for respiration and \( \sigma = 0.5 \times 10^{-10} \) for isotopic ratio). First, we fitted the parameters of the model system with decomposition formulation (10) and with decomposition formulation (3) to the timeseries of respiration. Second, we refitted the parameters by a multiple constraint approach to both the amount of respiration and the isotopic ratio.

The likelihood of the model parameters for this gaussian case with no apriori information on the parameters can be expressed as \( L = c \exp(-\frac{1}{2}SS) \), where \( c \) is a constant and \( SS \) is the weighted sum of squared differences between the vectors of the model output and the artificial data: \( SS = (g(m) - d_{obs})^T C_p^{-1} (g(m) - d_{obs}) \), where \( g(m) \) is the model output for the optimized parameters \( m \), and \( C_p \) is the variance-covariance matrix of the uncertainty of the observations \( d_{obs} \), in our case the artificial data (Tarantola, 2005). If ratio of the maximum likelihoods of the two formulations \( L_{ModelA}/L_{ModelB} \) increases with the multiple constraint analysis then the discrimination of the models is enhanced.

![Flowchart of the minimal decomposition model](image)

3 Results

3.1 Review of decomposition equations

3.1.1 Non-explicit representation of decomposer biomass in SOM decomposition

The most widely applied formulation of substrate decomposition is first order kinetics (Eq. 3) e.g. (Grace et al., 2006; Franko, 1996; Verberne et al., 1990; Hansen et al., 1991; Parton et al., 1988; Li et al., 1992; Molina et al., 1983; Chertov et al., 2001; Liski et al., 2005; Corbeels et al., 2005). The decomposer biomass is not treated explicitly. The formulation assumes that substrate of each quality, i.e. the ease of mineralisation (Paustian et al., 1997), has its own decomposer community associated with, and that this decomposer community is in equilibrium with the available substrate most of the time and therefore decomposition is only limited by substrate (McGill and Myers, 1987). Decomposition \( d_S \) therefore scales linear with available substrate \( S \).

\[ d_S = kS \]

Microbiology studies of substrate decomposition, however, show that decomposition often follows standard enzyme kinetics (Paul and Clark, 1989), where the rate of decomposition saturates at a maximum rate with increasing substrate availability (Eq. 4). Hence, several models use Michaelis-Menten type equations (e.g., van Dam and van Breemen, 1995).

\[ d_S = k \frac{S}{km + S} \]

Where, \( S \) is the quantity of carbon in recalcitrant SOM, \( k \) is the maximum decomposition rate and \( km \) is the quantity of \( S \) where decomposition rate is half of it’s maximum.

3.1.2 Linear representation of decomposer biomass in SOM decomposition

The assumption that decomposition is limited by substrate only has been questioned (Fontaine and Barot, 2005). Fontaine states, that decomposition of recalcitrant SOM is
limited by the quantity of enzymes and not by the quantity of
substrate. With the assumption that the quantity of enzymes
is proportional to quantity of carbon in the decomposer pool
A they propose Eq. 5, which was also already used by van
Wensem et al. (1997).

\[ d_S = kA \]  

(5)

The first order kinetics (Eq. 3) and Fontaine’s equation
(Eq. 5) can be seen as two extremes of a colimitation of de-
composition by substrate and decomposers. There are sev-
eral equations that take into account both quantities. The
probably simplest assumption is that decomposition is pro-
portional to both quantities \( A \) and \( S \) (Eq. 6) (Manzoni and
Porporato, 2007; Fang et al., 2005; Knapp et al., 1983).

\[ d_S = kAS \]  

(6)

According to Liebigs law of minimum Moorhead and
Sinsabaugh (2006) use Eq. 7, which is the minimum of of
Eq. 3 and Eq. 5, to describe decomposition. Also the for-
mulation of a mass-action law to describe the fraction of the
substrate that is decomposed by Neill and Gignoux (2006)
therefore leads to a decomposition that is smaller or equal
to this minimum.

\[ d_S = \min(k_1 S, kA) \]  

(7)

A classic formulation (Monod, 1949) is based on standard
enzyme kinetics (Eq. 8) with variable amounts of enzymes,
which are assumed to be proportional to the quantity of de-
composers. This formulation also has been frequently em-
ployed (Parnas, 1975; Smith, 1979; Van Veen and Frissel,
1981b; Ladd et al., 1995; Blagodatsky and Richter, 1998;
Kersebaum and Richter, 1994).

\[ d_S = kA \frac{S}{k_m + S} \]  

(8)

3.1.3 Nonlinear representation of decomposer biomass in
SOM decomposition

There are further formulations of colimitation that we distin-
guished from the previous ones because they are nonlinear in
respect to the decomposer quantity.

Besides standard enzyme kinetics, microbes may inhibit
each other (Suzuki et al., 1989). This kinetics can be de-
scribed by an increase of the \( k_m \) constant with increasing mi-
Crobial pool in the Monod-formulation (Eq. 8). Hence, Grant
et al. (2001) applied Eq. 9 to SOM decomposition.

\[ d_S = kA \frac{S}{k_m(1 + k_i A) + S} \]  

(9)

In a theoretical modelling study on the implications
of exoenzyme activity on microbial carbon Schimel and
Weintraub discussed several decomposition formulations
(Schimel and Weintraub, 2003). They proposed that the de-
composition rate saturates with increasing enzyme availabil-
ity instead of increasing substrate availability. With account-
ing for variable amount of SOM they derived Eq. 10. The
same equation has been used by other studies as well (Gar-
nier et al., 2003; Raynaud et al., 2006). The formulation is
structurally opposite to the formulation of Monod (Eq. 8),
which saturates with increasing SOM availability.

\[ d_S = kS \frac{A}{k_m + A} \]  

(10)

Using a simple simulation experiment of spatial accessi-
bility of microbial communities to a small soil volume Wutz-
ler (2008)\(^1\) inferred an exponential equation of the accessi-
ble proportion of the soil volume given the size of the decom-
poser pool. With the simplifying assumption that substrate is
randomly distributed within a small soil volume, decomposi-
tion then can be described by Eq. 11.

\[ d_S = k(1 - e^{-cA})S \]  

(11)

There are also more complex formulations of Eq. 12 in the
ITE model (Arah, 1996) and Eq. 13 in the SOMKO model
(Gignoux et al., 2001), for which we did not calculate equi-
librium states.

\[ d_S = kA^\frac{3}{2} \frac{S}{k_m + S}(1 - k_u \frac{A}{S}) \]  

(12)

\[ d_S = (1 - e^{-k_\frac{1}{2}})S \]  

(13)

3.1.4 Formulations of SOM decomposition with additional
states

Ågren and Bosatta (1996) propose a conceptual view of the
decomposition process, that involves a continuous spectrum
of quality of organic matter. Microbial access to the organic
matter, decomposition rate, and microbial efficiency depend
on the quality \( q \) of a litter cohort (Eq. 14) that changes during
decomposition.

\[ d_S = -\frac{k u(q)}{e(q)} S \]  

(14)

Blagodatsky and Richter (1998) propose a view on decom-
position that depends on the proportion of active to dormant
microbial biomass (Eq. 15). This proportion is expressed as
\(^1\)Wutzler, T.: Microbial accessible space as a limitation of SOM
T. Wutzler and M. Reichstein: comparison decomposition formulations

Table 1. Steady state of soil organic matter S∗.

<table>
<thead>
<tr>
<th>equation</th>
<th>dS</th>
<th>priming</th>
<th>S∗</th>
<th>scaling of S∗ with iF</th>
<th>S∗ at iF → 0</th>
</tr>
</thead>
<tbody>
<tr>
<td>non-explicit representations of decomposer biomass</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>kS</td>
<td>no</td>
<td>S</td>
<td>linear</td>
<td>0</td>
</tr>
<tr>
<td>4</td>
<td>k_S/(k_m+S)</td>
<td>no</td>
<td>(1-ε)S/(1-ε)</td>
<td>monotonous or ∞</td>
<td>0</td>
</tr>
<tr>
<td>linear representations of decomposer biomass</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>kA</td>
<td>yes</td>
<td>∞</td>
<td>no</td>
<td>S(t=0)</td>
</tr>
<tr>
<td>6</td>
<td>k_A &lt; kA</td>
<td>yes</td>
<td>k</td>
<td>no</td>
<td>S(t=0)</td>
</tr>
<tr>
<td>7</td>
<td>min(k_1S, kA)</td>
<td>yes</td>
<td>∞</td>
<td>no</td>
<td>S(t=0)</td>
</tr>
<tr>
<td>8</td>
<td>k_A_S/(k_m+S)</td>
<td>yes</td>
<td>k_m/k</td>
<td>no</td>
<td>S(t=0)</td>
</tr>
<tr>
<td>nonlinear representations of decomposer biomass</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>kA_S/(km(1+k_A)+S)</td>
<td>yes</td>
<td>k_m (k_A+1)</td>
<td>linear</td>
<td>S(t=0)</td>
</tr>
<tr>
<td>10</td>
<td>k_A_S/(km+S)</td>
<td>yes</td>
<td>k_m k_A</td>
<td>linear</td>
<td>S(t=0)</td>
</tr>
<tr>
<td>11</td>
<td>k_S(1-e^{-k_A})</td>
<td>yes</td>
<td>k_A</td>
<td>monotonous</td>
<td>S(t=0)</td>
</tr>
</tbody>
</table>

an activity state r which in turn is expressed as an additional state variable. r approaches a value that is a function of the substrate φ(S) (Eq. 16).

The formulations of SOM decomposition with additional states could not be represented with our minimal model. However, we refer to steady states in the original models in the discussion section.

3.2 Steady states

The steady state of the decomposer biomass A∗ is given by Eq. 18 for almost all the formulations. The only exception was formulation 5, where steady state of decomposer biomass follows Eq. 19. The constant c_1 introduced in equation 17 was introduced to simplify the equation 18 and the discussion of it. c_1 is always positive because ε<1, s>0, and r>0.

\[ c_1 = (1 - ε) s + r \]  
\[ A^* = \frac{i_F}{c_1} \]  
\[ A^* = \frac{i_F}{s + r - ε k} \]

The steady state for SOM (S∗) for the various formulations is given in Table 1. Formulations that did not result in a steady state are depicted by the symbol ∞. Fig. 2 displays the effect of the assimilation of FOM iF on the steady state for SOM (S∗).

![Fig. 2. Effect of assimilation rate of FOM iF on the steady state of SOM (S∗). The numbers refer to equations in the text.](https://example.com/fig2.png)
carbon inputs approach zero, also the decomposer biomass \( A^* \) goes to zero. However, \( S^* \) does not decrease to zero but stabilizes at a low level. Hence, in the absence of FOM assimilation there exists a fraction of SOM that is not decomposed. A similar behaviour is exhibited by formulation 9 for \( k>s \), i.e. when decomposition is greater than the turnover of microbial biomass. For \( s\rightarrow k \), \( S^* \) approaches infinity. And for \( k<s \) there is an infinite accumulation of SOM.

The continuous quality concept was not studied with our minimalistic model, which assumed only a single pool of SOM with given quality. Both, limited and unlimited accumulation can be simulated with the continuous quality concept. The result depends on the specification of the functions of microbial efficiency \( e(q) \), and the specific growth rate \( u(q) \) (Ågren and Bosatta, 1996). However, currently the priming effect is not simulated. All cohorts, i.e. carbon that entered the soil within the same time frame, decompose independently.

The steady state \( r \) in the model of Blagodatsky and Richter (1998) is given by \( \phi(S^*) \) Eq. 15 and Eq. 16. In the original model also the turnover of the microbes is modified by \( r \). With assuming a constant microbial turnover formulation 15 yields qualitatively same results for steady state as the Monod-kinetics (Eq. 8).

### 3.3 Artificial model calibration experiment

When using respiration data alone, it was hard to distinguish between the decomposition formulations (10) and (3) in the artificial model calibration experiment (Fig. 3a). However, the prediction of the isotopic ratio of the respired CO\(_2\) differed considerable (Fig. 3b). Hence, explicitly modelling the isotopic ratio and calibrating the models to both outputs, resulted already in a better discrimination of the models. The model of first order kinetics (3) slightly, but consistently underestimated the respiration during days 5 to 40 (Fig. 3c) and overestimated the isotopic ratio during these days (Fig. 3d).

The better discrimination between the formulations with the multiple constraint optimization was also seen in the ratio of the likelihoods of the two formulations. The maximum likelihood ratio (Schimel formulation 10/substrate first order...
formulation 3) was 1.5 with the fit to the amount of respiration alone, but it was 7.6\texttimes}11 with the additional inclusion of the isotopic ratio of the respiration.

4 Discussion

Our study provides the first review and comparison of soil organic matter decomposition models that explicitly focuses on the colimitation of decomposition by substrate and decomposers.

By abstracting from other factors such as fluctuations in environmental conditions or nutrient availability and by using a basic minimalistic model for all the equations, we could show that long term consequences of formulations do differ qualitatively. These differences could be grouped according to the assumptions about decomposer biomass and to the resulting representation of decomposer biomass in the decomposition equation.

4.1 Priming effect and steady states

The priming effect, i.e., the decomposition of SOM is influenced by the assimilation of FOM, was simulated with all formulations of SOM decomposition that accounted for active microbial biomass in an explicit manner (Table 1). The non-explicit formulations, used in many models (Sect. 3.1.1) were based on the assumption that decomposition of SOM can be considered in equilibrium with the available SOM at timescales larger than a few month (Paustian et al., 1997). If, however, the active SOM decomposers can feed on an additional carbon source related to FOM, this assumption does not longer hold. Contrary, the active decomposer biomass is near an equilibrium with the assimilation of FOM \( i_F \). Hence, in order to simplify models at larger time scales, we suggest to replace active decomposer biomass in model decomposition equations with the assimilation flux \( i_F \) and then simplify the system equations.

There was a finite steady state of SOM \( S^* \) with all formulations except the formulations 5 and 7. With the latter equations and also with formulations 4, 8, and 9 an unlimited accumulation of SOM was possible. In these cases other factors must limit SOM accumulation in order to not lock away all nutrients in SOM. Fontaine and Barot (2005) showed that competition for nitrogen between different microbial functional groups eventually limits carbon assimilation. Especially in older ecosystems also other nutrients such as phosphorus might be important. With these formulations the long-term balance is not determined by the quantity of litter input and decomposition rates only. Rather, parameters of the nitrogen cycle and nitrogen deposition become important. However, the understanding of nitrogen cycle is not equivocal in literature. For example there are competing hypothesis about direct or indirect nitrogen uptake (Manzoni and Porraro, 2007), damping or amplification of the priming effect by nitrogen fertilization (Fontaine et al., 2004; Conde et al., 2005), and the role of plants in competition for organic nitrogen (Schimel and Bennett, 2004). Further the nitrogen cycle may be strongly influenced by micro sites (Li et al., 2000). Hence, we expect that it will be hard to falsify the hypothesis of SOM accumulation to be limited by nitrogen.

The equilibrium state of SOM increased monotonically with input of fresh organic matter (FOM) in the non-explicit group of SOM decomposition formulations and the nonlinear group of formulations (Table 1). Contrary, with all formulations within the linear group the steady state was independent of FOM. This independence seems to contradict observations of environmental gradients of litter inputs, which are assumed to correlate with primary production, where carbon stocks are increasing with input of carbon (Jobbagy and Jackson, 2000; Paul et al., 1997). One argument was, that this positive correlation between primary production and SOM stocks is not due to litter production but due to other confounding factors. We believe, that this argument is unlikely, because temperature, the most important other factor, usually also increases with primary productivity. The temperature increase leads to increasing decomposition rates and possibly lower SOM stocks instead of higher SOM stocks (Table 1 Eq. 7).

The steady state for the case when FOM assimilation approached zero differed between the groups of formulations. Within the non-explicit group of formulations SOM steady state \( S^* \) was zero, i.e., all SOM is eventually decomposed (Fig. 2). With all the other formulations, there was an offset for SOM steady state \( S^* \) for reasonable model parameterization and initial conditions. For the formulations 5 and 7, which did not lead to a general steady state, the amount of the SOM pool did not change and stayed at the amount before FOM assimilation decreased to zero (Table 1). For the formulations in the non-linear group, the SOM pool decreased but approached a positive amount. Hence, there was a part of the SOM that is not decomposed at all in the absence of available fresh organic matter. This finding corresponds to observations of Fontaine et al. (2007) of millenia-years old carbon (Rumpel et al., 2002; Jobbagy and Jackson, 2000) in deeper soil layers where FOM supply is very low (von Lützow et al., 2006). It also corresponds to observations of litter bag studies, which can be best modelled by inferring a limit of decomposition where there is a part of the initial mass that is not decomposed in finite time (e.g. Berg et al., 1996; Bottner et al., 2000).

The strength of the approach of using a common basic model to compare different formulations of SOM decomposition is also its biggest limitation. We could not compare the behaviour of the continuous quality model (Agren and Bosatta, 1996) and the activity state model (Blagodatskyy and Richter, 1998). The abstraction from other factors such as temperature, moisture, and nutrients discards aspects that are important in the original context of the equations. However, inclusion of other aspects would yield in more complex and
quantitatively larger differences in the steady state behaviour of the different models.

4.2 Relation with temperature sensitivity

The formulations of decomposition based on substrate only have lead to the models with the smallest number of state variables and parameters, properties that are favourable in modelling. However, the assumptions that decomposer biomass is in equilibrium with the SOM pool neglects the priming effect and results in long-term behaviour that can explain very old carbon only by assuming a very low intrinsic decomposability. With these equations the decomposition of old carbon is primarily controlled by the temperature sensitivity of the old carbon (e.g. Reichstein et al., 2005).

Contrary, temperature sensitivity may be overruled by other factors when explicitly modelling the priming effect by a second food source to the SOM decomposers and when explicitly accounting for decomposers in the SOM decomposition. The steady state of old SOM depends either on other limiting factors such as nitrogen (Fontaine and Barot, 2005) (linear group of formulation). Or it depends on the availability of energy-rich fresh organic matter, belowground litter, or root exudates (Godbold et al., 2006; Göttlicher et al., 2006) which vary with soil depth (Bruun et al., 2007; Rasse et al., 2006; Gill and Burke, 2002; Frey et al., 2003; Elzein and Balesdent, 1995) (nonlinear group of formulation). The latter dependency is sensitive to land use changes, management practices and soil perturbations.

The importance of temperature sensitivity of SOM decomposition strongly affects our understanding of the feedback of SOM to global warming. We conclude that it is necessary to study which assumptions and which formulations of decomposition are more or less suitable to represent the most important drivers for long term carbon balance.

4.3 Challenging models with experiments to discriminate among formulations

In the following section we discuss approaches of discriminating among the different formulations. Often experiments are designed to calibrate a given model, or a model is designed to explain the observed data. Most of the cited models have been repeatedly compared to observations that were collected to validate the model. However, science usually works the opposite direction where inappropriate hypotheses are falsified or ranked down by comparison against observation data Popper (1934); Kuhn (1962); Lakatos (1977). Therefore, we argue to design experiments in a way that models can be falsified in the best way (Hunter and Reiner, 1965; Atkinson and Donev, 1992; Reynolds and Ford, 1999). When sorting out models that are less suitable to explain the observed data, we also challenge the assumptions that underlie the models and the formulations of SOM decomposition.

The first idea of discriminating among the models is to challenge the long-term behaviour of the models (Fig. 2) by observations of carbon stocks for soil that are assumed to be in steady state and to compare the scaling of the soil carbon stocks with the mean litter input. The finding of increasing SOM stocks with increasing primary productivity and litter input (Jobbagy and Jackson, 2000; Paul et al., 1997) renders the formulations in the linear group unlikely. However, we already discussed the possible influence of confounding environmental factors. The effect of temperature, soil moisture, texture and structure has to explicitly accounted for in both observations and modelling. Further, the assumption that recently undisturbed soils are near steady state has been questioned, because of the long turnover times of the slow carbon pools (Wutzler and Reichstein, 2007).

Hence, we suggest to study the transient behaviour of soil under laboratory conditions, where the confounding factors and the input of fresh organic matter are controlled. We propose to challenge models by observations of patterns of several variables, which is used in multiple constraint model identification (Raupach et al., 2005; Reichstein et al., 2003) or pattern oriented modelling (Wiegand et al., 2003). The inclusion of the isotopic ratio in addition to the amount of respiration clearly improved the identifiability of model formulations in the artificial model discrimination experiment. However, the addition of the isotopic ratio might not sufficient in other cases and we need to look for additional measures and patterns. A closer collaboration between soil scientists, microbiologists, modellers, and experimentalists is required to set up sound models and experiments in order to solve the model identification task.

If experiments can show that the priming effect is important for the long-term dynamics of SOM, the formulations of the non-explicit group are less suitable to describe long-term SOM dynamics. The discussion on the positive correlation between litter input and steady state SOM stocks rendered also the formulations of the linear group unlikely. Hence, we argue that the formulations of SOM decomposition where the active decomposers are represented in a nonlinear manner are most suitable to describe long-term SOM dynamics.

5 Conclusions

This study reviews and compares different assumptions and formulations of colimitation of SOM decomposition by substrate and decomposers. The substitution of several formulations into a common basic model and the calculation of steady states enabled to compare the long term consequences of the formulations and their underlying assumptions. We showed that the consequences of various formulations can be grouped according to the representation of active decomposer biomass in the decomposition of SOM.

- The assumption that decomposition kinetics of various OM pools is independent of each other together with
the assumptions that decomposers are quickly in steady state with substrate supply leads to formulation of decomposition that use substrate only. The priming effect is not simulated and SOM pools eventually decrease to zero on exhaust of FOM supply.

- The assumption that SOM decomposition is linearly related to decomposer biomass leads to steady states of soil organic matter that are independent of assimilation of FOM. Other factors such as nutrient limitation must be invoked to limit carbon sequestration.

- Several non-linear formulations of SOM decomposition exhibit similar steady state behaviour. Steady state SOM stocks increase monotonous with supply of FOM. At the exhaust of FOM assimilation, the decomposition is slowed down and there is a fraction of the SOM which is not decomposed.

Various assumptions lead to qualitatively different long-term behaviour of soil organic matter dynamics. In order to resolve these contradictory consequences, a combined effort of experimentalists and modellers is needed to identify which of the competing assumptions and models are suitable for describing long term carbon dynamics for which soils. If one accepts the assumptions that the priming effect is quantitatively important for SOM dynamics and that the steady state SOM stocks increase with litter input, then we argue that the formulations of SOM decompositions, where the active decomposers are represented in a nonlinear manner are most suitable to describe long-term SOM dynamics.

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